	(3 Hours) [Total Marks	:: 80]
N.B:	(1) Question No.1 is compulsory.	
	(2) Answer any three questions from Question Nos. 2 to 6.	
	(3) Assume suitable data if necessary.	
1	Answer any FIVE of the following questions:-	2 4 9 20 9 5
	(a) Draw and explain the block diagram of process control.	4
	(b) Explain Dead Time. Why dead time systems are difficult to control?	4
	(c) Discuss types of variables associated with process control.	64
	(d) State significance of continuous control actions.	4
	(e) Justify the need of Adaptive control?	4
	(f) Explain in brief relative gain analysis (RGA).	4
2	(a) Compare pneumatic and electronic PID controller.	10
	(b) What is inverse response behavior? Explain how to compensate inverse response behavior of a chemical processes.	10
3	(a) Discuss various controller modes and explain working of ON/OFF controller.	10
	(b) Explain block diagram analysis for MIMO system.	10
4	(a) Explain advantages and disadvantages of feedback/feed forward control strategy.	10
	(b) Explain dynamic behavior of Second order systems with suitable sketches.	10
5	(a) Why tuning of controller is required? Explain process reaction curve method for tuning.	10
	(b) Explain with a neat sketch cascade control scheme for CSTR.	10
6	Write Short Notes on:	0.7
	(a) PLC.	05
	(b) Proportional Band and Offset.	05
	(c) Ratio control scheme.	05
5 5 5	(d) Interacting System & Non Interacting system.	05

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Paper / Subject Code: 37402 / POWER ELECTRONICS AND DRIVES

Time: 3 Hours Tota	
NB. Q.1 is Compulsory. Solve any four questions from the remaining.	
 Q1 a) Explain SCR ratings b) compare IGBT & MOSFET c) Explain Commutation in Thyristor circuit d) Differentiate between series & parallel inverter 	20
Q2. Design a converter to give output voltage 120 V at 1A los 50 Hz ac supply. Use UJT 2N2646. V _{BBmax} = 35 V for Vbb=16 V, C=0.1μF, η _{min} =0.56, η _{max} = Iv=4mA, Ip=25μA Consider temperature compensation.	
Q3 a) with the help of a neat diagram and associated waveforms d converter. Also list the advantages and disadvantages of this b) Explain variable frequency I.M. drive.	
 Q4 a) Describe the working of 1phase fully controlled bridge con 1) Rectifying mode 2) Inversion mode. Also sketch the following waveforms for α=45°, & α= 	
b) Write a note on control strategies used in chopper.	10
Q 5 a) Explain the application of power electronics in industrial b) Explain application of triac as an ac regulator. Draw rele	- -
 Q6 a) Explain PWM inverter with appropriate waveforms b) Explain full bridge inverter with R-L load. Also explain diodes in these inverters. 	n purpose of feedback 10

[Time: 3 Hrs] [Marks: 80]

Please check whether you have got the right question paper.

N.B: 1. Questions No 1 is compulsory.

- 2. Solve any three questions of the remaining five questions.
- 3. Assume any suitable data if required.
- Q. 1 Answer the following (any four) (20)
 - a) Find the energy of the signal $x(n) = 0.2^n u(n) + 5^n u(-n-1)$
 - b) Find the value of x (n) = $\cos (0.25\pi \text{ n})$ for n = 0, 1, 2, 3 Compute the DFT of x(n) using FFT flow graph.
 - c) Compare FIR and IIR filter.
 - d) State and prove the circular time shift property of DFT.
 - e) Write a short note on Decimation by a integer factor.
- Q. 2 a) Determine the output of a Linear FIR filter whose impulse response $h(n) = \{3, 7, 1, \}$ (10) For input $x(n) = \{5, 0, -2, 1, -3, -1, 0, 2, -3, 1, 4, 2\}$ Using overlap save method.
 - b) Derive and draw the FFT flow graph for N=6=2x3 using DITFFT algorithm. (10)
- Q. 3 a) Perform circular convolution using DFT and IDFT. $x(n) = \{1, -5, 3, 2\} \text{ h}(n) = \{2, 7, 4, 1\}$ (10)
 - b) Obtain DF-I, DF-II and cascade form of realization for the system Y(n) = -0.1 y (n-1) + 0.2 y (n-2) + 3x(n) +3.6 x (n-1) + 0.6 x (n-2)(10)

(10)

Q. 4 a) A LPF has the desired response as given below:- $\begin{pmatrix}
-j3w & \pi
\end{pmatrix}$ (10)

 $\operatorname{Hd}\left(e^{jw}\right) = \begin{cases} e^{-j3w} & 0 \le \omega \le \frac{\pi}{2} \\ 0 & \frac{\pi}{2} \le \omega \le \pi \end{cases}$

Determine filter coefficients h (n) for N = 7, using frequency sampling technique.

b) A Low pass filter has the following specifications

 $0.8 \le | H (e^{jw}) | \le |$ $0 \le \omega \le 0.2 \pi$ $| H (e^{jw}) | \le 0.2$ $0.7 \pi \le \omega \le \pi$

Find filter order and cutoff frequency.

- i) By BLT method
- ii) By IIT method used for design
- **Q. 5** a) Frequency response of a filter is given by an expression. $h^{(ejw)} = e^{-j3w} [2 + 1.8 \cos 3w + 1.2 \cos 2w + 0.5 \cos w]$ Find impulse response of filter. (05)
 - b) The Transfer function of analog filter is $h(s) = \frac{1}{(s+1)(s+3)}$ [05] Find H[z] using Impulse Invariance method.

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Paper / Subject Code: 37403 / DIGITAL SIGNAL PROCESING

	C)		$(\mathbf{u}\mathbf{s})$
		{20, 0, -4+4j, 0, -4} be the first 5 points of 8 point DFT X [K] of a real value sequence x(n).	9
	i)	Find X [K] for $K = 5, 6, 7$	700
	ii)	Find the 8 point DFT P[k] such that p (n) = $(-1)^n$ x(n) using DFT property.	
			300
Q. 6	a)	Explain the architecture of any DSP processor with major blocks.	(10)
	b)	Explain any one application of DSP	(05)
	c)	Explain relationship between ZT, DTFT and DFT	(05)
			37.65

3 HOURS

[TOTAL MARKS: 80]

N. B.	(1) Question No. 1 is compulsory.(2) Attempt any Three questions out of remaining five questions.	
	(3) Assume any suitable data if necessary.(4) Figure to the right indicates full marks.	
1.	Attempt any four.	20
	 a) States important features of PIC18F microcontroller. b) Draw and explain ADC modules of PIC18Fmicrocontroller. c) Explain SPI module of PIC18F microcontroller. d) Explain basic concept of RTOS. e) Explain following instructions with example: DECFSZ BTFSS RETFIE. 	
2.	a) Define embedded system. States various characteristics and design challenges of embedded system.	10
	b) What is task? Explain various task scheduling algorithms for RTOS.	10
3.	a) Draw and explain block diagram of PIC18Fmicrocontroller.	10
	b) Explain CCP module of PIC18F microcontroller in capture and compare modes.	10
4.	a) Write a program to load number 7FH in WREG and subtract it from the number 28H and display the result at PORTC and also save it in registers 30H. Identify the status of all the flag after the subtraction.	s 10
~~	b) Write a program to copy the value 55H into RAM locations 40H to 45H using Direct and Register Indirect Addressing (without loop) Modes for PIC18F microcontroller.	10
5.0	a) Write a program to toggle RB1 a total of 200 times. Use file register of RAM Location 32H to hold counter value.	10
	b) Interface 4x4 matrix key with PIC18F and explain it operation in detail.	10
6.	a) Interface a Stepper Motor to PIC18F microcontroller and write a program to control the angle and direction of Stepper Motor rotation.	10
	b) Write a short note on Inter-integrated Circuit (I ² C) Protocol.	10
	\$\6\2\3\\$\6\8\6\8\\\\\\\\\\\\\\\\\\\\\\\\\\\\	

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(Total Marks: 80)

(**3 Hours**)

<u>Note:</u> 1.	Question No.1 is compulsory	30
1. 2.	Solve any THREE questions out of remaining FIVE questions.	
3.		
3.	Figure to the right indicate full marks.	ON A
1. Ans	swer any five:	(20)
	a) Explain the importance of Hubs, routers, switches and bridges.	NO.
	b) What are the components of a field bus?	E DE DE
	c) Compare H1 and HSE segments of foundation field bus.	
	d) Explain the difference between physical address, network address and domain name	ne.
	e) Explain ethernet.	
	f) Mention the ISO-OSI layers along with their functions.	
		2,01
2. Ans	swer the following:	FA
	a) What is meant by sensor level network? Explain two such networks in detail.	(10)
	b) Compare WiFi, GSM, GPRS wireless communication technologies.	(10)
	49449999999444444444444444444444444444	
3. Ans	swer the following:	
	a) Explain the OPC-OLE and list its importance.	(10)
	b) Explain PROFIBUS in detail.	(10)
1 A		
4. Ans	swer the following:	(10)
	2 2 2 V 8 V 2 0 8 2 2 V 8 2 6 8 2 6 8 6 8 8 8 8 8 8 8 8 8 8 8 8	(10)
	b) Explain MODBUS in detail.	(10)
5 Ano	swer the following:	
J. Alls	a) Explain the architecture of HART and its importance in industrial communication.	(10)
	5 72 74 0 74 75 0 5 7 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	(10)
	b) Explain the circuit switching, packet switching and message switching.	(10)
6. Wri	ite short notes on any (2):	(20)
	a) CAN Bus	()
	b) Transmission impairments in communication	
2007	c) IEEE standards and Token bus.	
	282444448924904488	
2002	505957444868 <u>490</u> 7	
S. E. C.		
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Paper / Subject Code: 37406 / ANYLYTICAL INSTRUMENTATION

	Duration: 03 Hours	Total Marks: 80
Note:	 Question No. 1 is compulsory. Answer any three questions from the remaining five questions. Assume suitable data wherever necessary. 	
Q1. A	nswer any 4 from the given 5 questions:	20
	 a) Give 4 differences between Fluorescence and Phosphorescence. b) Justify that Beer-Lambert's law is a limiting law. c) Differentiate filters and monochromators. d) Explain any 4 characteristics of Raman lines. e) What is chemical shift and give its significance in NMR. 	
Q2.	a) With a neat diagram, explain working of Single beam spectrophotor	neter. 10
	b) Describe with a neat diagram phosphoriscope.	10
Q3.	a) Explain working and application of Scintillation counter with neat d	iagram. 10
	b) Explain working of Atomic Emission Spectrometer with application	10
Q4.	a) Explain the working of Nuclear Magnetic Resonance (NMR) Spectr	cometer. 10
	b) Explain the working GC-MS with a neat diagram.	10
Q5.	a) Explain principle and working of Time-of-flight type mass spectron	neter. 10
	b) Explain with a neat diagram the working of gas density analyzer.	10
Q6.	Write short notes on: (any two)	20
2000 C	a) HPLC	
	b) X-ray absorption meter	
	c) Double beam Fluorimeter	
1,42,40	9333 4 9 8 8 8 8 9 9 8 ° 8 ° 8 ° 8 ° 8 ° 8 ° 8	